




MXS-EVO

Disciplined RF Generator

Rev 1.7

Dichiarazione di conformità Declaration of conformity	
La Ditta <i>The Company</i>	DIGITAL INSTRUMENTS S.r.l. Via Parco degli Scout, 13 20091 BRESSO (MI) ITALY
Dichiaro con la presente che il Prodotto <i>Herewith declares that the Product</i>	
Tipo / <i>Type</i>	Disciplined RF Generator with Multiple Sources
Modello / <i>Model</i>	MXS-EVO
Serial Number	0140 /
Oggetto di questa dichiarazione è conforme ai seguenti standard o norme della Comunità Europea <i>Referred to by this declaration is in conformity with the following standards or normative documents of EC</i>	
Norme Europee Armonizzate <i>European Armonized Standards</i>	
CEI EN 61000-6-4:2007	Electromagnetic compatibility (EMC) - Part 6-4: Generic standards - Emission standard for industrial environments
CEI EN 61000-6-2:2006	Electromagnetic compatibility (EMC) - Part 6-2: Generic standards - Immunity for industrial environments
CEI EN 55011:2011	Limits and methods of measurement of radio disturbance characteristics of industrial, scientific and medical (ISM) radio-frequency equipment
CEI EN 61000-4-2:2011	Electromagnetic compatibility (EMC) - Part 4-2: Testing and measurement techniques - Electrostatic discharge immunity test
CEI EN 61000-4-3:2007+A1:2009+A2:2011	Electromagnetic compatibility (EMC) - Part 4-3: Testing and measurement techniques - Radiated, radio-frequency, electromagnetic field immunity test
CEI EN 61000-4-4:2006+A1:2010	Electromagnetic compatibility (EMC) - Part 4-4: Testing and measurement techniques - Electrical fast transient/burst immunity test
CEI EN 61000-4-5:2007	Electromagnetic compatibility (EMC) - Part 4-5: Testing and measurement techniques - Surge immunity test
CEI EN 61000-4-6:2011	Electromagnetic compatibility (EMC) - Part 4-6: Testing and measurement techniques - Immunity to conducted disturbances, induced by radio-frequency fields
CEI EN 61000-4-8:1997+A1:2001	Electromagnetic compatibility (EMC) - Part 4-8: Testing and measurement techniques - Power frequency magnetic field immunity test
CEI EN 61000-4-11:2010	Electromagnetic compatibility (EMC) - Part 4-11: Testing and measurement techniques - Voltage dips, short interruptions and voltage variations immunity tests
CEI EN 60204-1:2006+A1:2010	Safety of machinery - Electrical equipment of machines - Part 1: General requirements
Bresso, October 2012	DIGITAL INSTRUMENTS S.r.l. Via Parco degli Scout, 13 20091 BRESSO (MI) ITALY <i>Marco Genova</i> <i>Quality Assurance Manager</i>

Istruzioni di sicurezza Safety Instructions

Il dispositivo è stato progettato, costruito e collaudato in conformità alle normative richiamate nel Certificato di Conformità ed è stato rilasciato dal costruttore completamente testato secondo gli standard di sicurezza. Per mantenere questa condizione e assicurare la sicurezza d'uso, l'utente deve osservare tutte le istruzioni e segnalazioni di pericolo descritte in questo manuale.

This unit has been designed and tested in accordance with the EC Certificate of Conformity and has left the manufacturer's plant in a condition fully complying with safety standard. To maintain this condition and to ensure safe operation, the user must observe all the instructions and warnings given in this operating manual.

- **Prima di mettere in servizio il dispositivo, leggere attentamente ed integralmente le istruzioni per l'uso. Osservarle e seguirle in tutti i punti. Provvedere in modo che le istruzioni per l'uso siano sempre accessibili a tutti gli addetti.**

Prior to switching on the unit, please read carefully the instructions on the manual. Keep this manual available for all every user of this equipment.

- **Il terminale PE sul dispositivo deve essere connesso al conduttore PE prima di eseguire qualsiasi altra connessione. L'installazione ed il cablaggio devono essere eseguiti da personale tecnico qualificato.**

The PE terminal of the unit must first be connected to the PE conductor on site before any other connections are made. Installation and cabling of the unit to be performed only by qualified technical personnel.

- **Lo strumento supporta alimentazione AC wide range da 95 Vac a 240 Vac e deve essere connesso tramite protezione con corrente nominale massima pari a 16A.**

This unit may be operate from wide range AC supply networks from 95 Vac to 240 Vac fused with max. 16A.

- **Lo strumento supporta alimentazione DC wide range da 20 Vdc a 50 Vdc e deve essere connesso tramite protezione con corrente nominale massima pari a 5A. Il circuito di protezione contro l'inversione di polarità è implementato a bordo.**

This unit may be operate from wide range DC supply networks from 20 Vdc to 50Vdc fused with max. 5A. Circuit against polarity inversion is also implemented.

Le condizioni di sicurezza vanno testate ad ogni sostituzione. Ispezione visiva dei cavi, stato dell'isolamento, corrente di dispersione, stato del connettore PE e test funzionale.

A safety test must be performed after each replacement of part. Visual inspections, PE conductor test, insulation resistance, leakage-current measurement, functional test.

- **Non interrompere il conduttore PE in nessun caso. Un'interruzione del cavo PE rende l'apparato elettricamente pericoloso.**

It is not permissible to interrupt PE conductor intentionally, neither in the incoming cable nor on the unit itself as this may cause the unit become electrically hazardous.

- **Ogni riparazione, manutenzione e sostituzione del dispositivo deve essere eseguita unicamente da personale autorizzato dalla Digital Instruments.**

Any adjustments, replacements of parts, maintenance or repair may be carried out only by authorized Digital Instruments technical personnel.





- **Assicurarsi che ogni collegamento con dispositivi informatici sia eseguito secondo IEC950/EN60950**

Ensure that the connections with information technology equipment comply with IEC950/EN60950

Simboli di sicurezza Safety Symbols

Sono presenti sul dispositivo e nella documentazione simboli utilizzati per la segnalazione di segnalazione conformi alle specifiche IEC61010-1 II.

Safety-related symbols used on equipment and documentation comply with IEC 61010-1 II.

	<ul style="list-style-type: none"> • SIMBOLO DIRECT CURRENT IEC 417, N°5031 Vdc may be used on rating labels
	<ul style="list-style-type: none"> • SIMBOLO ALTERNATING CURRENT IEC 417, N°5032 For rating labels, the symbol is typically replaced by V and Hz as in 230V, 50Hz.
	<ul style="list-style-type: none"> • SIMBOLO PROTECTIVE CONDUCTOR TERMINAL IEC 417, N°5019 This symbol is specifically reserved for the PROTECTIVE CONDUCTOR TERMINAL and no other. It is placed at the equipment earthing point and is mandatory for all grounded equipment
	<ul style="list-style-type: none"> • SIMBOLO CAUTION ISO 3864, N°B.3.1 used to direct the user to the instruction manual where it is necessary to follow certain specified instructions where safety is involved.

Changelog

Rev.	Note	Data
1.0	First revision	30/11/2011
1.1	Updated and fixed revision	16/03/2012
1.2	Added programmable outputs details	11/04/2012
1.3	Added note about the internal NTP server	18/04/2012
1.4	Added section about Custom Settings	30/10/2012
1.5	Updated changelog	02/05/2013
1.6	Added notes about the NTP server timestamping	14/10/2013
1.7	Added FAQ section	31/10/2013

MXS-EVO

Disciplined RF Generator with Multiple Sources

Index

Summary	6
Front View	7
Rear View	7
Connectors details	8
Main Operation	10
GPS	10
External Reference (EXT)	10
E1	10
NTP	12
PTP (IEEE 1588)	13
IRIG-B	14
Date and time	15
Switchover Function	16
Switch Policies	16
Switchover Treshold	16
Graph Menu	19
WEB Interface	22
Event Log	30
SNMP Trap Management	31
User Account	31
Custom Settings	32
First Run	33
Appendix A: Quality Factor	35
General Review	35
GPS antenna positioning	35
Quality Factor	36
Statistics	37
Automatic Site Survey	37
Appendix B: FAQ	38
Appendix C: Changelog	41
Assistance	43
Technical Data	44

Summary

This manual provides to the user of the apparatus **MXS-EVO** all the information necessary for proper operation. The informations include the normal installation procedures and any data on the maintenance and programming in order to facilitate interventions in the field.

MXS-EVO is a multiple output signal generator able to reconstruct stable time-frequency references (10MHz, PPS, 2.048MHz, E1, IRIG-B).

It is composed of a GPS receiver and accepts in input a frequency RF signal, a timing RF signal, an E1 multiframe signal and an IRIG-B signal. It is possibile to use any or all of these references to use the internal high stability OCXO. In the standard version there are 12 independent programmable outputs in any of the possible configurations (10 MHz, PPS, 2.048 MHz, E1, IRIG-B AM, IRIG-B DC), 1 E1 input and 1 E1 output, 1 time input and 1 frequency input, 1 optical IRIG-B input, 1 optical IRIG-B output, 1 TTL IRIG-B input (may be used in place of the external timing input).

MXS-EVO is a very flexible solution suited to all those applications where is necessari to provide a stable time-frequency reference to multiple devices. whilst mantaining electrical isolation.

When an error on the selected source is observed an error condition is generated via SNMP and dry contacts and a new source is selected between the available ones as per user configured priority.

MXS-EVO is quite simple to use and to set-up. Every function can be accessed locally from the LCD panel and remotely via WEB or SNMP.

MXS-EVO gives informations about its internal status via 7dry contacts placed on the rear panel and the LEDs on the front panel.

MXS-EVO has double Power Supply Unit, to ensure best safety and uninterrupted work.

MXS-EVO is in metallic box of sizes 1U 19'' for rack installation.

Note

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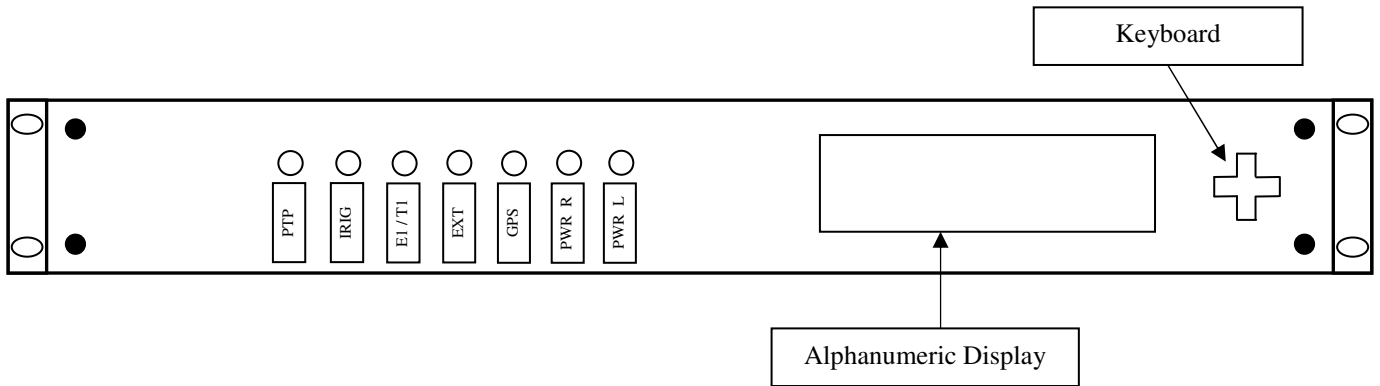


WARNING: Before inserting the power supply please carefully read all instructions for proper installation.

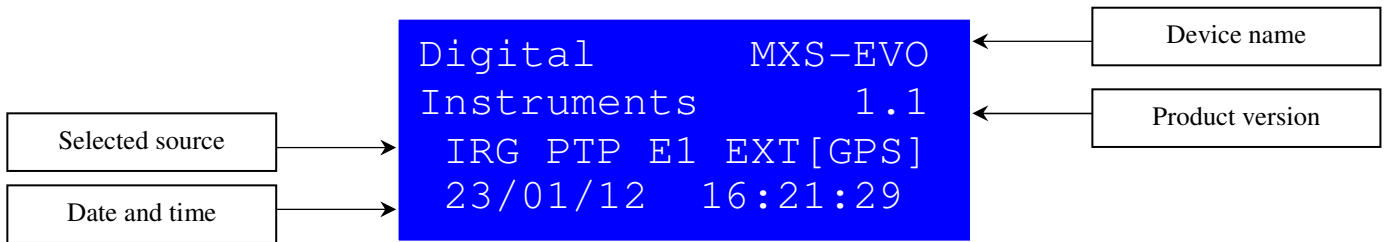
Front View

The front panel appears as shown in the following figure.

On the left side there are the two removable modules, whilst on the right can be found an alphanumeric 20x4 display and a keyboard.



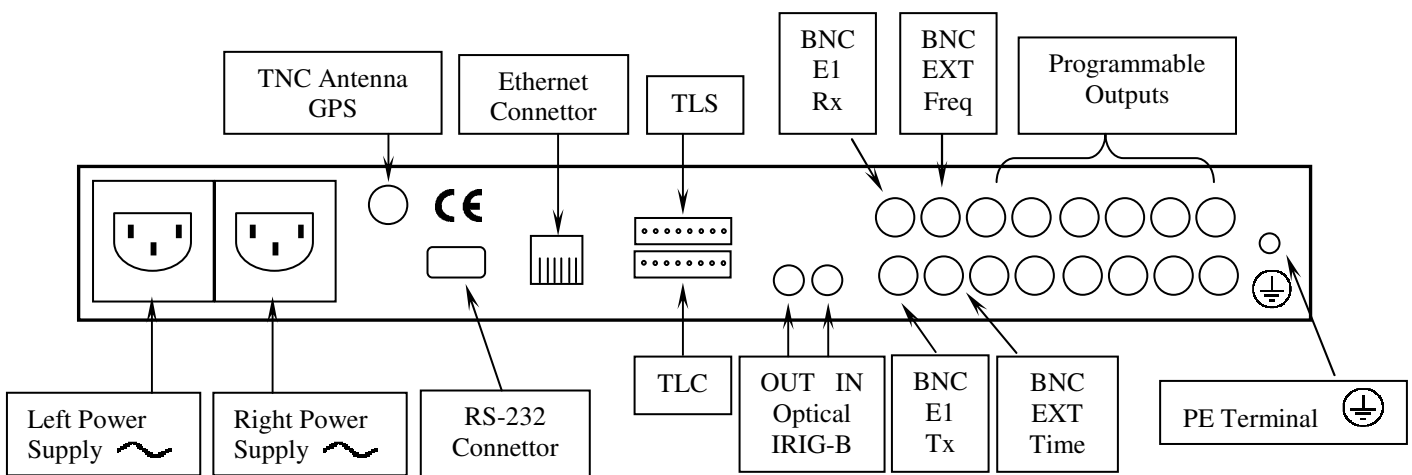
In modo operativo sul display vengono visualizzati alcuni parametri come nell'esempio sotto:



By pushing the right keyboard button it's possible to enter the main menu of the **MXS-EVO**.

Rear View

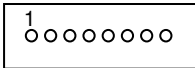
In the following figure is depicted the back of the apparatus **MXS-EVO** with the position of connectors.



The MXS-EVO does not provide any supply switch.

Connectors details

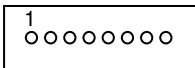
TLS connector (Remote signals)



The 8 poles TLS connector provides the following information on the various pins (from left to right):

- PIN 1: Common contact
- PIN 2: Closed contact → Right power supply provided
- PIN 3: Closed contact → Left power supply provided
- PIN 4: Closed contact → GPS reference present and valid
- PIN 5: Closed contact → EXT reference present and valid
- PIN 6: Closed contact → E1 reference present and valid
- PIN 7: Closed contact → PTP reference present and valid
- PIN 8: Closed contact → Synchronization completed

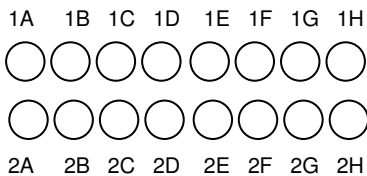
TLC connector (Remote controls)



The 8 poles TCL connector provides the following commands on the various pins (from left to right):

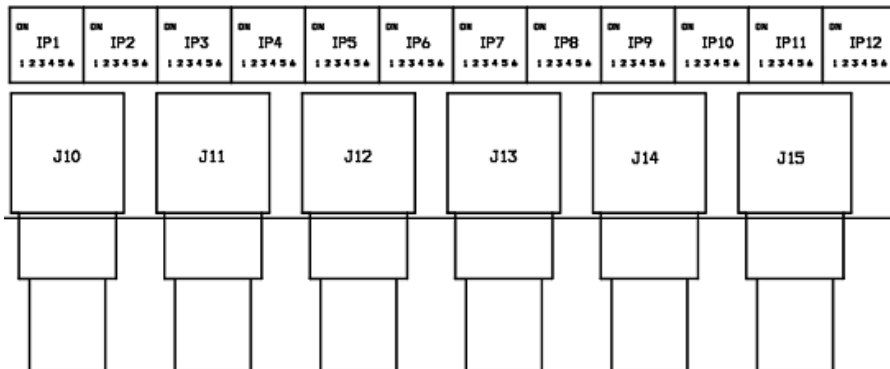
- PIN 1-2: Closed contact → Manual switch
- PIN 3-4: Closed contact → Automatic switch
- PIN 5-6: Closed contact → Switch over previous reference
- PIN 7-8: Closed contact → Switch over next reference

Programmable outputs

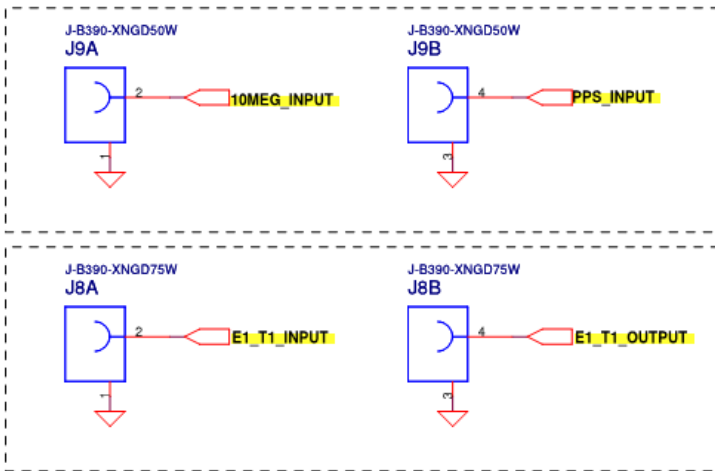


A technical sheet about the programmable outputs is given alongside the device. The following table can be taken as reference to understand it.

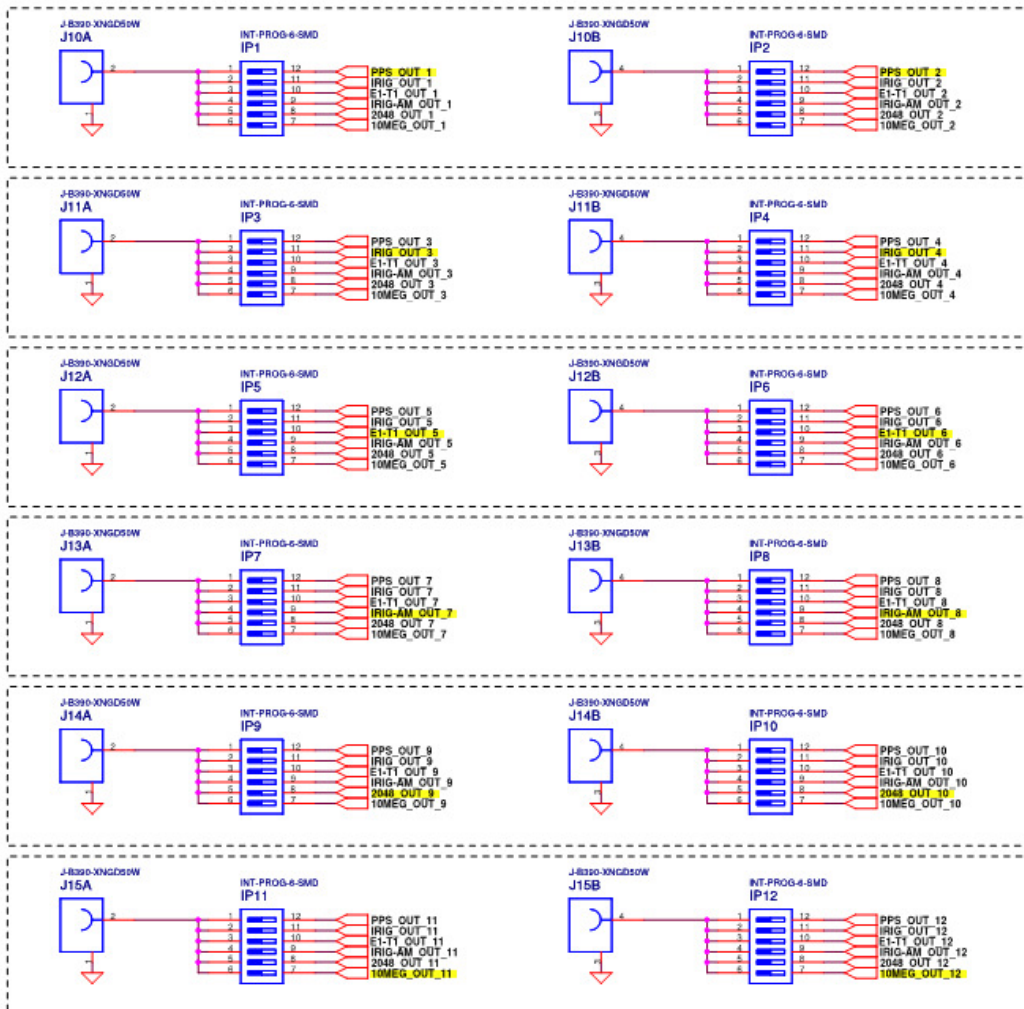
J8A → 1A	J9A → 1B	J10A → 1C	J11A → 1D	J12A → 1E	J13A → 1F	J14A → 1G	J15A → 1H
J8B → 2A	J9B → 2B	J10B → 2C	J11B → 2D	J12B → 2E	J13B → 2F	J14B → 2G	J15B → 2H



Four connectors have fixed functions that cannot be altered:



Twelve connectors have instead customizable functions by means of a DIP switch matrix placed on the PCB inside the device:



Even if modifying the outputs is simple is suggested to first contact the factory in order to avoid voiding the warranty by opening the device.

Main Operation

The main purpose of the *MXS-EVO* is to provide stable output signals of Time (PPS, E1, IRIG code, NTP/PTP) and Frequency (10 MHz, 2.048MHz), and to enable the synchronization of the network.

This is allowed by the application of algorithms, tuning an high-stability internal oscillator.

Peculiarities of the *ETS-EVO* is the possibility to accept input from four different sources:

1. GPS
2. EXTERNAL REFERENCE
3. E1
4. PTP (IEEE 1588)
5. IRIG-B

In this manner it is possible to switch from one source to another, if a fault occurs.

The strong difference between the various sources is a major strength as it makes the same apparatus both very flexible to suit the needs of the customer and very strong in order to better cope with possible failures of a type of source (for example, the loss of accuracy of the GPS signal).

Even in case of a switch, references of Time / Frequency provided are kept stables.

GPS

The apparatus is internally equipped with a GPS receiver especially suitable for use as a time reference. The GPS receiver is able to reproduce the local PPS signal relative to UTC second with a precision of typically ± 100 ns. With this feature is possible to regulate the internal oscillator apparatus for producing a high-stability output signals.

External Reference (EXT)

The MXS-EVO accepts a frequency input and a timing input on two distinct BNC connectors.

These are the frequencies recognized:

- 1MHz
- 2MHz
- 2.048MHz
- 5 MHz
- 10 MHz

This are the timing values recognized:

- 1 PPS

The device, when using the external frequency reference as source generates the internal PPS based on the last received timing pulse from another reference.

It is possible to tune the internal OCXO in phase (slower, but keeping phase alignment) or in frequency (much faster, but the phase alignment is lost). With the timing input only the phase disciplinino mode is supported.

This behaviour can be set under *Disciplining Mode*.

When both a frequency and time references are given, the latter ha more priority and is automatically chosen to maintain a phase alignment.

E1

The E1 signal, standardized by the European Conference of Postal and Telecommunications Administrations (CEPT) and subsequently adopted by the International Telecommunication Union Telecommunication Standardization Sector (ITU-T), operates at a nominal value of 2.048 Mbps and

is widely used in digital telecommunications worldwide, with the exception of USA and Canada (where the T1 signal is in use) and Japan (where is in use the J1). The E1 link operates on two separate coaxial cables (Rx and Tx).

Also in this case it's possible perform a rapid frequency locking with the 2.048 MHz reference of E1 signal, setting the *Disciplining Mode* voice to the *frequency* value.

Status Informations

MXS-EVO allows to view the status of the E1 module through the following values:

- Presence or absence of E1 signal
- Presence or absence of E1 framing
- SSM Quality (Rec. ITU-T G.704, see below) of the synchronization source
- Bit Error Rate is calculated by the BERT (see below)
- BERT Irq Array, binary array of interrupt requests that triggered errors generated in BERT (see below)
- Delay between the E1 PPS and the PPS generated by OCXO

Available Settings

MXS-EVO allows the possibility to set the device as a supplier of synchronization signal E1 (E1 Master), in case where it's connected to valid synchronization sources (GPS, cesium oscillator, etc.), or as a sevice receiver of E1 synchronization signal (E1 Slave). In the first case, it is also possible to choose the quality of the source, according to the table of Recommendation G.704 (ITU-T):

Quality Level	Value Displayed	Description of Sync Quality Level
0	Unknown	Quality Unknown (existing synchronization network)
1	Reserved	
2	G.811	Recommendation G.811
3	Reserved	
4	SSU-A	Synchronization Supply Unit A (Note 1)
5	Reserved	
6	Reserved	
7	Reserved	
8	SSU- B	Synchronization Supply Unit B (Note 1)
9	Reserved	
10	Reserved	
11	SETS	Synchronous Equipment Timing Source (SETS)
12	Reserved	
13	Reserved	
14	Reserved	
15	DON'T USE	Do not use for synchronization
Note 1: In previous versions was used the terms "G.812 transit" and "G.812 local", for more information, see Rec G.812 (ITU-T)		

MXS-EVO allows to choose on which of the 30 (from 2 to 32, excluding 17) timeslots of the E1 frame transmit the PPS signal. As default, the signal is sent and received on timeslot 32. The timeslots 1 and 17 are used to send sync and control data by E1. The PPS is implemented by putting up only the LSB of the selected timeslot.

MXS-EVO allows to test the quality of the physical channel on which the E1 signal is transmitted activating the Bit

Error Rate Test (in reception and / or transmission), and choosing which of timeslots (except for the one used for the PPS and, advising against the first, where the sync data are sent) to receive and / or send the signal for the test. The form of the Bit Error Rate Test can generate and detect pattern both pseudo-random and repetitive. It's used to test and stress the channels of communication data. Has been set the pseudo random pattern QRSS for testing. The apparatus allows to show the value of the bit error rate and the log of interrupts that have generated errors in the BERT, the latter is defined thus: 0X1X2X3X4X5X60 where:

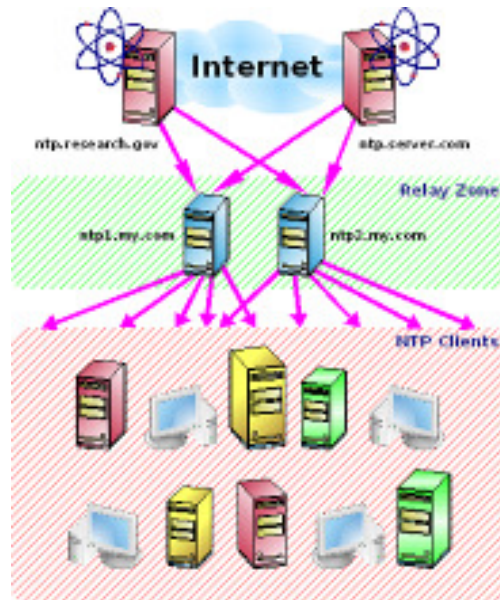
- X1 passes from 0 to 1 occurs when the reception of an error;
- X2 passes from 0 to 1 when an overflow occurs in the counter total BERT;
- X3 goes from 0 to 1 when an overflow occurs on the BERT error counter;
- X4 changes from 0 to 1 when received 32 '1' row;
- X5 goes from 0 to 1 when received 32 '0' row;
- X6 from 0 to 1 when there is loss of synchronization;

MXS-EVO allows to choose which "column" (from 4 to 8) of bits use to transmit the value of the signal quality. By default this value is sent and received on the column 8.

NTP

The NTP (Network Time Protocol) is a well-established standard for synchronization of PCs and other devices on the Internet or an Intranet network.

The accuracy of the order of tens of milliseconds, can be considered adequate for most situations. Its flexibility and strength, thanks to the many servers widely available, making it a very smart choice for time synchronization.



The device supports NTP server version 4 that distributes the synchronous time related to an external time reference (typically GPS, PTP or IRIG-B).

To achieve better performance hardware timestamping is supported, but in this case PTP support is disabled. When using hw timestamping the precision of the hardware timestamps in the NTP packet is better than 100 ns.

In order to use this feature the client has to support the interleaved mode¹, enabled with the following statement:

```
peer <server ip> true iburst xleave prefer
```

In order to use the broadcast mode authentication has to be disabled in the client configuration with the following statements:

```
disable auth
broadcastclient
```

¹ <http://www.eecis.udel.edu/~mills/ntp/html/xleave.html>

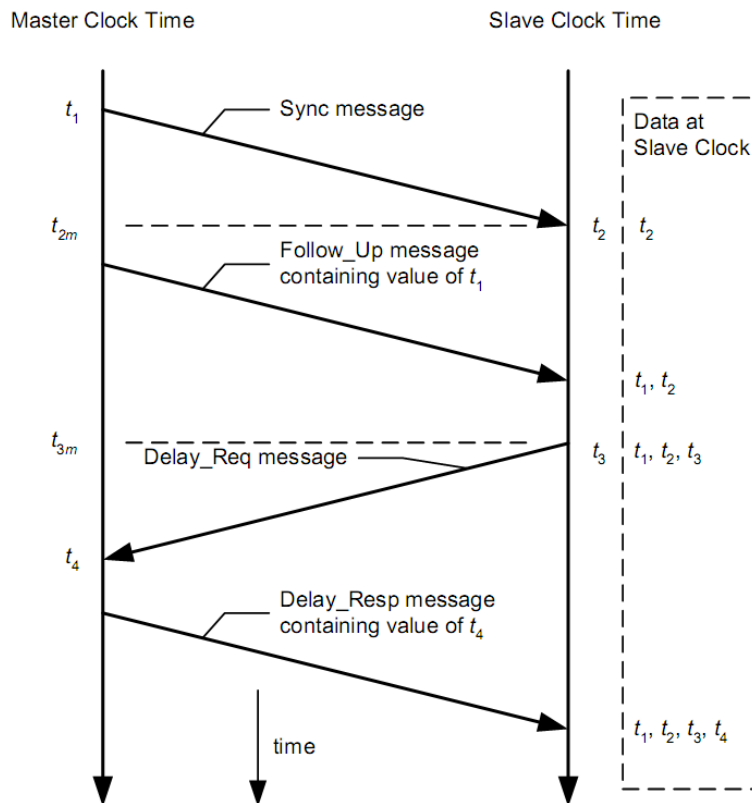
PTP (IEEE 1588)

The **MXS-EVO** supports the IEEE 1588-2008 (version 2), also known as *Precision Time Protocol*, both as master and slave. When connected to an appropriate device compatible to the IEEE 1588 standard is able to synchronize the slave apparatus with a precision well below the micro-second.

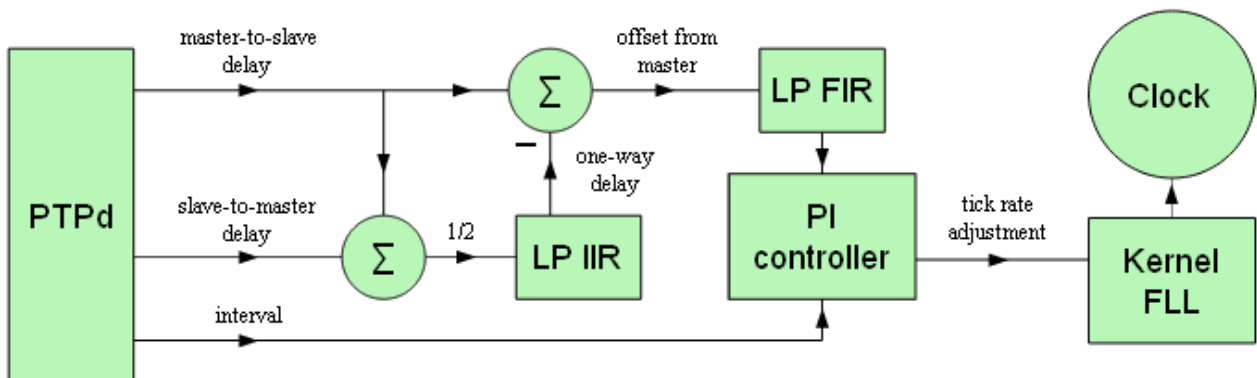
Note that using network switches non-compliant with IEEE 1588, variable delays in the order of some tens of microseconds are introduced (as noted in the official website of the Protocol <http://ieee1588.nist.gov/switch.htm>).

The IEEE 1588 bases its operation on the calculation of the transit time of PTP packets from the master to the slave (and slave to master).

These latencies are calculated using a simple exchange of messages between master and slave that are associated with timestamps managed at the hardware level.



Once reconstructed the one-way-delay it is possible to use it to correct the clock of the slave and lock it to the master. Below is shown the pattern of the loop relative to the clock tuning based on PTP.



IRIG-B

The device can accept in input and provide in output (on BNC and optical connectors) an IRIG-B stream of type 006, compliant with following code:

Bit position	Information transmitted
0	Position identifier P _R (seconds' boundary marker)
1–4	Units of seconds
6–8	Tens of seconds
9	Position identifier P ₁
10–13	Units of minutes
15–17	Tens of minutes
19	Position identifier P ₂
20–23	Units of hours
25–26	Tens of hours
29	Position identifier P ₃
30–33	Units of days
35–38	Tens of days
39	Position identifier P ₄
40–41	Hundreds of days
49	Position identifier P ₅
50–53	Units of year or control function bits
55–58	Tens of year or control function bits
59	Position identifier P ₆
60–68	Control function bits
69	Position identifier P ₇
70–78	Control function bits
79	Position identifier P ₈
80–88	Nine lowest significant bits of time of day in straight binary seconds (bit 80 → 2 ⁰ ... bit 88 → 2 ⁸)
89	Position Identifier P ₉
90–97	Eight most significant bits of time of day in straight binary seconds (bit 90 → 2 ⁹ ... bit 97 → 2 ¹⁶)
99	Position identifier P ₀
Note: Bits not listed are index markers, and are sent as binary zeroes.	

It was also implemented part of the standard 1344-1995. The offset compared to the UTC time can be set using the Timezone of the apparatus. Changes of DST or leap second are not currently notified (always returned as 0).

IRIG-B Pos ID	CTRLB IT#	Designation	Explanation
P50	1	Year, BCD 1	Last 2 digits of year in BCD
P51	2	Year, BCD 2	IBID
P52	3	Year, BCD 4	IBID
P53	4	Year, BCD 8	IBID
P54	5	Not used	Unassigned
P55	6	Year, BCD 10	Last 2 digits of year in BCD
P56	7	Year, BCD 20	IBID
P57	8	Year, BCD 40	IBID
P58	9	Year, BCD 80	IBID
P59	-	P6	Position identifier # 6
P 60	10	Leap second pending (LSP)	Becomes 1 up to 59 s BEFORE leap second insert
P 61	11	Leap second (LS)	0 = Add leap second, 1 = Delete leap second
P62	12	Daylight saving pending (DSP)	Becomes 1 up to 59 s BEFORE DST change
P63	13	Daylight savings time (DST)	Becomes 1 during DST
P 64	14	Time offset sign	Time offset sign – 0=+, 1=-
P65	15	Time offset-binary 1	Offset from coded IRIG-B time to UTC time IRIG coded time plus time offset (including sign) equals UTC time at all times (offset will change during daylight savings)
P 66	16	Time offset-binary 2	
P 67	17	Time offset-binary 4	
P68	18	Time offset-binary 8	
P 69	-	P7	Position identifier # 7
P70	19	Time offset-0.5 hour	0 = none, 1 = additional 0.5 h time offset
P71	20	Time quality	4 b code representing approx. clock time error 0000 = clock locked, maximum accuracy 1111 = clock failed, data unreliable.
P72	21	Time quality	
P73	22	Time quality	
P74	23	Time quality	
P75	24	PARITY	Parity on all preceding data bits
P76	25	Not used	Unassigned
P77	26	Not used	Unassigned
P78	27	Not used	Unassigned
P79	-	P8	Position identifier # 8

The device can output both an IRIG-B DCLS and IRIG-B AM signals. It can also recognize an IRIG-B DCLS signal via a BNC or optical connector. When the BNC connector is used it inhibits the external timing input.

Date and time

The device disciplines its internal clock from the selected reference (GPS, PTP, IRIG-B, NTP) and distributes it with the following rules:

- NTP (UTC timebase as per standard)
- PTP (TAI timebase as per standard)

Switchover Function

ETS-EVO allows the possibility to switch the disciplining of its internal timebase selecting one of many sources. This exchange can be configured to run automatically upon occurrence of an alarm condition, such as:

- PPS signal absence
- disconnection of the antenna
- error in the external source
- error in the E1 signal
- error in the PTP protocol
- error in the IRIG-B signal

In the log are reported the reason of the switch:

Mweb	→ user defined switch from WEB
Msnmp	→ user defined switch from SNMP
Mlcd	→ user defined switch from LCD
Mopto	→ user defined switch from TLC
Aser	→ automatic switch due to serial connection lack of GPS
Aant	→ automatic switch due to connection lack of GPS antenna
Apref	→ automatic switch to the higher priority source
Aext	→ automatic switch caused by an error in the external signal
Ae1	→ automatic switch caused by an error in the E1 signal
Aptp	→ automatic switch caused by errors in the PTP protocol
Airigb	→ automatic switch caused by an error in the IRIG-B signal

Switch Policies

The **MXS-EVO** permits to chose the priorità of the various sources.

Priorità is bigger when the value is bigger. 0 inhibits the source.

When the device is configured for automatic switchover two different policies can be used:

Switch & Free

The device switch to the best available source when an error is recognized on the actually selected source.

Switch & Pref

The device always switch to the source with highest priority currently available, if valid.

In order to avoid the possibility of continuos alarms due to intermittent switches there is a check that does not permit to switch more than 3 times in 5 minutes, by automatically lowering the policy (*Switch & Pref* → *Switch & Free*).

This event has been given the following code:

Event Code 007 Switch Alarm → Done more than 3 switches in less than 5 minutes

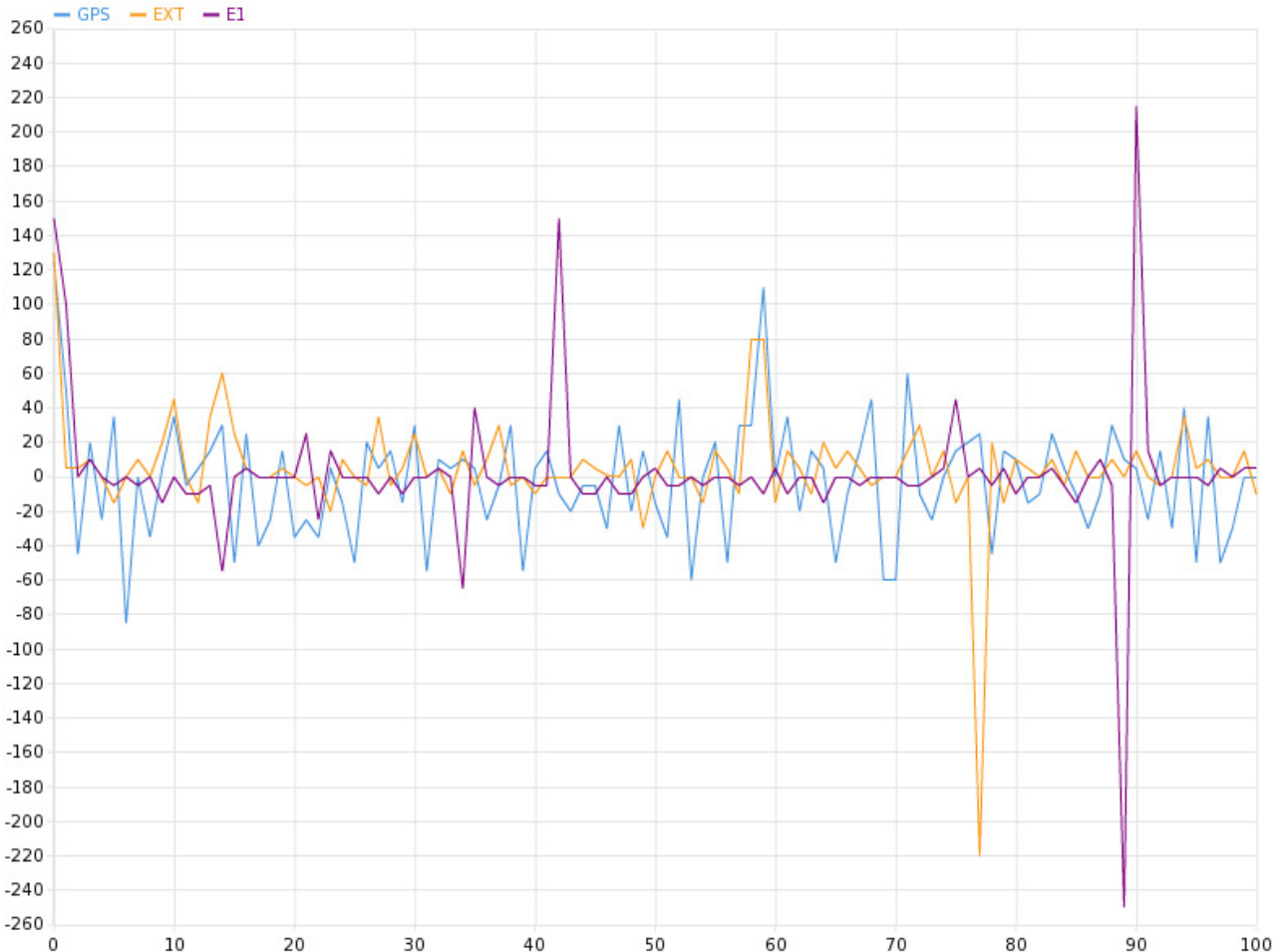
Switchover Treshold

This variable allows to define a time interval (in seconds) that must elapse between the time when an error has been identified and when it will be exchanged effectively. If during this time the error will disappear, the exchange will be deleted.

Characterization of Sources

MXS-EVO was also designed to compare the quality of the different sources provided to apparatus, analyzing the ratio $\Delta f / f$ (variation of the frequency value on the nominal frequency) of each source. This analysis is supported by a graph (that can be generated by the *Stability Chart* button in the *Main Panel*) which shows the trend of these ratios over time.

The step used is 5 minutes, while the values are expressed in nanoseconds.



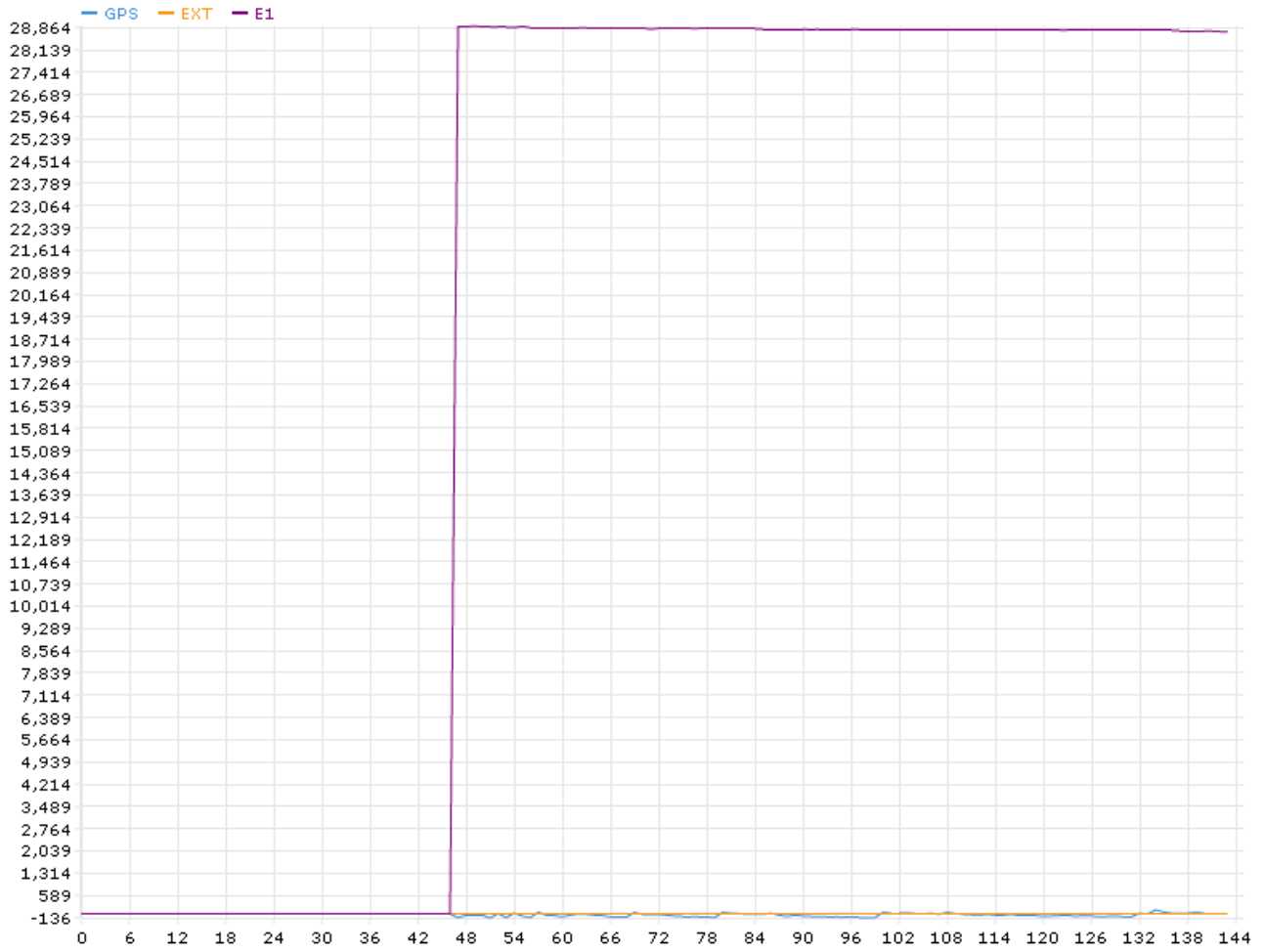
Moreover, is also possible display both on web interface (the *View* section of *Main Panel*), and on the LCD screen (below the status of each source), the delay, expressed in nanoseconds, between the PPS generated from the apparatus output and the three different tuning sources.

To correctly perform the characterization of various sources it's good configure the equipment with the following settings:

- Manual mode exchange
- GPS Source selected

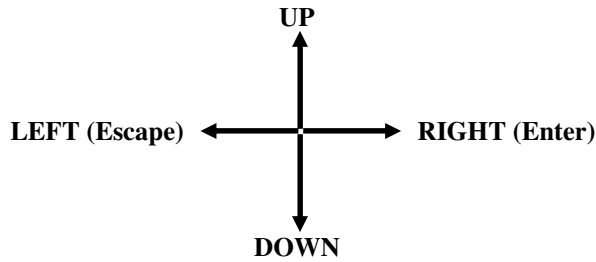
It's good practice also expect that the PPS generated by the radio is valid and that its delay is close to 0 ns (visible from GPS → status).

It is also possible display the progress of these distances over time (using the button *Distance Chart* in the *Main Panel*).



Graph Menu

The graph menu can be navigated with the pressing of the four direction provided by the keyboard.



To enter the first level from level zero (**ROOT**) is enough to press the **RIGHT** key, that works as **Enter** key. At this point all the first level menus are visible in a cyclic loop with the pressing of the **UP** and **DOWN** keys. The currently selected menu is recognized by an arrow placed on its left side. It is possible to enter it by pressing the **RIGHT** key.



By entering a menu is possible to view all of its associated submenus by pressing the **UP** and **DOWN** keys. The **RIGHT** key permits, once again, to enter the selected submenu in the view mode. By pressing **RIGHT** again is possible to modify the value of the parameter (an arrow indicates the modify mode). **RIGHT (Enter)** confirms the choice, whilst **LEFT (Escape)** discards it.



The changing of parameters from front panel is only supported in local mode.

From the level 0 (**ROOT**) it is possible to change the contrast of the LCD screen by pushing the **UP** and **DOWN** keys.

In the following table the whole graph is shown, with the associated permitted values for each parameter.

Front Panel Menu		Values
Mode Menu	Local/Remote	Local / Remote
Network	IP Address	0.0.0.0 ÷ 255.255.255.255
	Gateway	0.0.0.0 ÷ 255.255.255.255
	Netmask	0.0.0.0 ÷ 255.255.255.255
	MAC Address	00:00:00:00:00:00 ÷ ff:ff:ff:ff:ff:ff
	DHCP	ON / OFF
	Trap Dest	0.0.0.0 ÷ 255.255.255.255
	Trap Port	0 ÷ 65535
	Log Dest	0.0.0.0 ÷ 255.255.255.255
	Log Port	0 ÷ 65535
Board Settings	Source	GPS / EXT / E1 / PTP / IRIG-B (only possible in manual switch)
	Manual/Auto	Manual / Auto
	Disciplining Mode	Phase / Frequency
	Policy	Switch & Free / Switch & Pref
	Switchover	0 ÷ 36000s (10 hours)
	Priority	GPS: 0 ÷ 5 EXT: 0 ÷ 5 E1: 0 ÷ 5 PTP: 0 ÷ 5 IRIG-B: 0 ÷ 5 0 = [], 1 =[#], 2=[##],3=[###], 4=[####], 5=[#####]
	PPS Mute	ON / OFF
	Holdover	0 ÷ 999999 s
	PPS Mux Out	PPS, IRIG-B, PULSE #1, PULSE #2
	IRIG-B Mux Out	PPS, IRIG-B, PULSE #1, PULSE #2
Board Status	Info	SW/HW version
	Disciplining	Vtune value: 0 ÷ 65536 PPS Sync: ON / OFF
	Stability	Δf/f for each source measured in the past 10 minutes
	Show Statistics	Holdover Num, Holdover Max, Quality Min, PPS Dist Max, Pos Alarm Num, Reset
	TLC	4 values → 0, 1
	TLS	7 values → 0, 1
	Supply	AC L: ON / OFF AC R: ON / OFF
GPS	Status	Radio: OK / Unplugged TD: <value> [ns]
	Positioning Mode	Normal Position, Position Hold, Altitude Hold, Autosite Survey
	Latitude	-89° 59' 59'' ÷ 89° 59' 59''
	Longitude	-179° 59' 59'' ÷ 179° 59' 59''
	Height	0 ÷ 18000 mt
	Cable Delay	0 ÷ 10000 ns
	T-Raim Alarm	300 ÷ 1000000 ns
	Restore Defaults	Restore
	Show Ch Status	Ch, S/N, Elevation, Azimuth
Show Global Info	Tracked Sats, Visible Sats, PPS Signal, Antenna	

EXT	Frequency Ref.	Value: <frequency value> [Hz] Valid: YES / NO Tolerance: ± <value> [Hz]
	Time Ref.	Period: <period value> [ms] Valid: YES / NO Tolerance: ± <value> [ms] TD: <value> [ns]
	Settings	Accepted frequency: 1MHz - 2MHz - 2.048MHz - 5 MHz - 10 MHz Accepted time: 1 PPS
E1	Status	Signal Status: No Signal / OK Framing Status: No Framing / OK SSM Quality Level: <SSM quality received> Bit Error Rate: <value> BERT Irq Array: 00000000 ÷ 01111110 TD: <value> [ns]
	Board Type	Slave / Master
	SSM Quality Sent	<SSM quality sent> (only in E1 Master mode)
	PPS Timeslot Rx	2 ÷ 32 (17 excluded)
	PPS Timeslot Tx	2 ÷ 32 (17 excluded)
	BERT Rx	ON / OFF
	BERT Tx	ON / OFF
	BERT Timeslots Rx	ON / OFF for 32 timeslots (from 1 to 32)
	BERT Timeslots Tx	ON / OFF for 32 timeslots (from 1 to 32)
	SSM Column Rx	4 ÷ 8
SSM Column Tx	4 ÷ 8	
PTP	Status	Status: UNKNOWN / SLAVE / MASTER / ... TD: <value> [ns]
	Enabled	ON / OFF
	Board Type	Slave / Master
	Jitter	1 ÷ 255
	Unicast	ON / OFF
	Dest	0.0.0.0 ÷ 255.255.255.255
	Priority	0 ÷ 255
	Profile	DEFAULT, TELECOM, POWER
IRIG-B	Status	Present YES / NO Date Date and Time TD: <value> [ns]
	IRIG-B Mux In	Optical / Electrical
Setup	Date & Time	00:00:00 01/01/01 ÷ 23:59:59 31/12/99
	Timezone	-12 ÷ 12
	Clear Log	Clear
	Restore Defaults	Restore
	Reboot	Reboot

WEB Interface

The MXS-EVO is managed by the network using a common browser by simply connecting to the associated IP address.

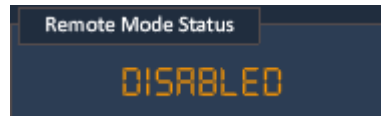
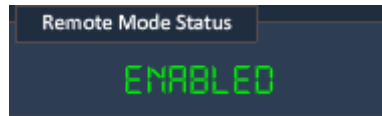
Mode Menu

Local/Remote

In local mode is only possible to modify operative parameters from the front panel display. In remote mode it can be done from WEB, SNMP and REMOTE CONTROLS.

In the WEB interface this value is visible in the *Remote Mode Status* field. When *Disabled* is shown no operation can be made to change the operative status of the apparatus.

Please note that the value of this parameter can only be changed by the front panel.



Network Configuration Panel

The screenshot shows the Network Configuration Panel with the following fields:

- Board ID:** BOARD
- Trap Dest:** 0.0.0.0 (with a 162 bit field)
- Ethernet 1:** IP: 192.168.200.36, Netmask: 255.255.255.0, Gateway: 192.168.200.254
- Ethernet 2:** IP: 10.0.0.36, Netmask: 255.255.255.0, Gateway: 10.0.0.254
- Buttons:** Save, RESET & REBOOT, RESET TO DEFAULT, REBOOT THE BOARD

Board ID

Allows to define a name to the apparatus, useful for identifying it on the network

Trap Dest

Allows to configure the destination server of the traps related to the events.

IP

Allows to set up the IP address associated to the the specific network interface. To activate the changes, system needs to restart.

Netmask

Allows to set the netmask associated to specific network interface. To activate the changes, system needs to restart.

Gateway

Allows to set the gateway associated with specific network interface. To activate the changes, system needs to restart.

Reset to default

Restores the original configuration

Reboot the board

Restarts the device

Date & Time

Allows to view/set the date and time of the apparatus. Note that this will still be automatically updated to that received by satellite.

Timezone

Allows to set the UTC offset for proper time visualization.

This setting determines the IRIG-B time offset.

Guest Account Settings

Allows to change the credentials of the user account (see below for more details)

Admin Account Settings

Allows to change the credentials for the administrator account (see below for more details)

The screenshot shows three panels:

- Date & Time:** Month: 7, Day: 14, Year: 2011, Hours: 13, Mins: 23, Secs: 39, Timezone: GMT: +0:00 (universa), Save button.
- Guest Account Settings:** Username: guest, Password: ***** (with Show characters checkbox), Save button.
- Admin Account Settings:** Username: admin, Password: (with Show characters checkbox), Save button. A warning message states: "For security reasons password will not be loaded."

Board Config Panel

Source

Permits to force a switch on a different source when the device is configured in manual switch mode. To switch from the WEB interface just go the the *View* tab of the *Main Panel* and click on a source.

Manual/Auto

Allows to set the type of switching (manual or automatic).

Disciplining Mode

Selects the kind of tuning to use when disciplining from da EXT or E1 reference. The frequency tune is faster, but loses the phase alignment of the PPS provided in output.

Policy

Indica la politica attualmente utilizzata per la commutazione in modalità automatica. Per avere maggiori Indicates the policy used to do switchovers. Toh ave more details on the subject please consult the relative section *Switchover Policies*.

Switchover

Allows to modify the switch-over time. For more details please consult the relative section *Switchover*.

Priority

Set the priority of each source for the automatic switch (a higher value means a higher priority, 0 disables the source).

PPS Mute

Inhibits the output of the PPS until the device has reached a synchronized status (typically a few minutes are needed).

PPS

Allows to choose which signal to spread on the PPS connectors (default is board PPS).

IRIG-B IN

Permits to choose the source of the IRIG-B input signal (BNC or OPTICAL)

IRIG-B OUT

Allows to choose which signal to spread on the IRIG-B BNC connectors (default is IRIG-B).

Positioning

Permits to change the position of the device (retrieved from GPS if available).

The screenshot shows a web interface for configuring the board. It is organized into several sections:

- Switch Mode:** A dropdown menu set to "automatic".
- Switch Policy:** A dropdown menu set to "Switch and Pref".
- Switchover:** A numeric input field set to "0" with a "sec" label and up/down arrows.
- Discipling Mode:** A dropdown menu set to "Phase".
- Holdover:** A numeric input field set to "0" with a "sec" label and up/down arrows.
- PPS Mute:** Radio buttons for "On" and "Off", with "Off" selected.
- Positioning:** Three input fields for "Latitude: 45.543930 °", "Longitude: 9.195100 °", and "Altitude: 206.450000 m".
- Priority:** Five numeric input fields with up/down arrows: IRIG-B: 5, PTP: 2, E1: 3, EXT: 4, GPS: 5.
- Mux:** Three dropdown menus: PPS: PPS, IRIG-B IN: OPTICAL, IRIG-B OUT: IRIG-B.

Board Status



Overview

Permits to view the status of all the sources alongside their time reference comparison with the internal reference.

Info

Displays the name of the device and the corresponding software release. The ID field can be customized by the user to track the device.

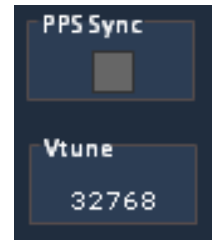
These informations are displayed in the *Board Info* panel of the main page of the WEB interface.



Disciplining

Shows the current disciplining value given to the internal oscillator and the synchronization status.

These informations are reported in the *PPS Sync* and *Vtune* values on the *Main* panel.



TLC

Shows the status of the 4 TLC

- 0 → TLC inactive
- 1 → TLC active

TLS

Shows the status of the 7 TLS

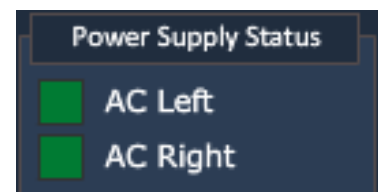
- 0 → TLS inactive
- 1 → TLS active



Supply

Shows the status of the 2 power supplies (left and right).

- OFF → power supply inactive
- ON → power supply active



GPS

Status

Displays some informations about the GPS radio.
If present and its time delay in respect to the internal PPS.

Positioning Mode

Permits to set the way in which the GPS module should calculate its geographical position. If extract it from the information collected from the satellites or using the one given by the user.
The “Altitude Hold” mode may not be available on every GPS module.

Latitude

Permits to view/set the latitude of the GPS antenna.

Longitude

Permits to view/set the longitude of the GPS antenna.

Height

Permits to view/set the height of the GPS antenna.

Cable Delay

Permits to set the length of the antenna cable connected to the GPS module, so to compensate the delays introduced by the signal propagation

Show Ch Status

Shows the status of the channels of the GPS receiver
The snr, the elevation and the azimuth of the visible satellites are reported
To cycle through the various channels use keys ↓ and ↑.

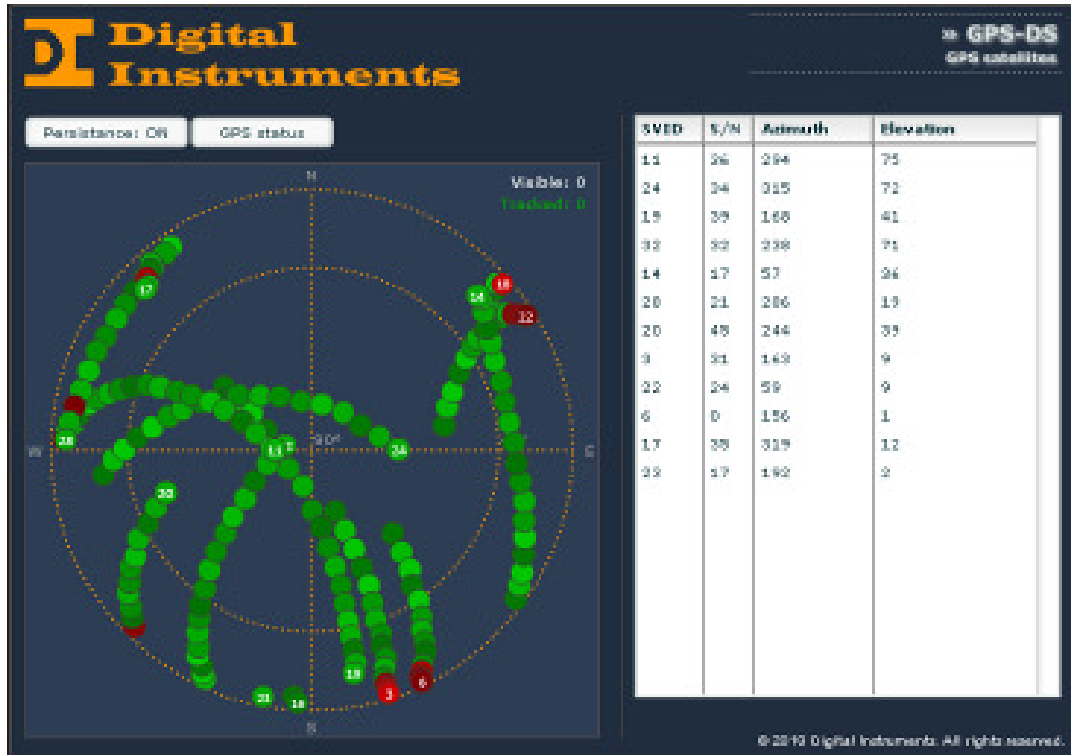
Show Global Info

Shows some info about the GPS module:
 Visible Sats → the number of visible satellites
 Tracked Sats → the number of tracked satellites
 PPS Status → the status of the PPS signal
 Antenna → the status of the antenna

All these variables are reported in the *GPS status* window. *Cable Delay* can be set in the *GPS Configuration*, whilst *Latitude*, *Longitude* and *Height* cannot be set by WEB, but only from SNMP or front panel.



The satellite view can be opened by pressing the *Polar view* button.



EXT

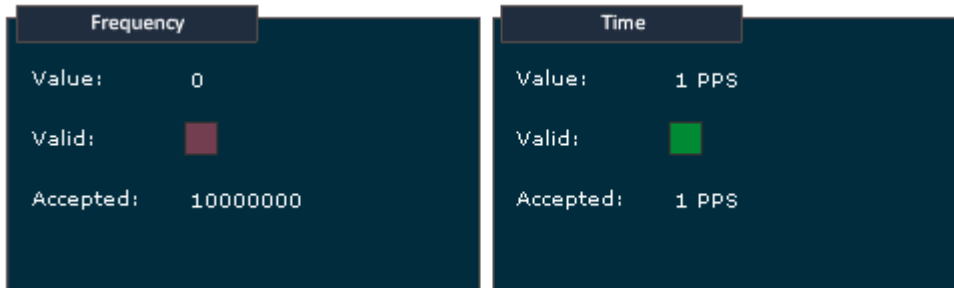
Frequency Ref.

It allows to display the frequency reference, expressed in Hz, which is currently supplied as an input to the apparatus and if this value has been accepted. Its acceptance or not depends on the value set as acceptable and on tolerance (viewable by pressing ↓).

Time Ref.

Allows to display the time reference, expressed in PPS (pulse per second) or in ms, currently supplied as input if this value has been accepted. Its acceptance or not depends on the value set as acceptable and on tolerance (viewable by pressing ↓).
It also indicated the time delay (TD) of the external time reference and measured respect to the PPS signal outputted from the apparatus.

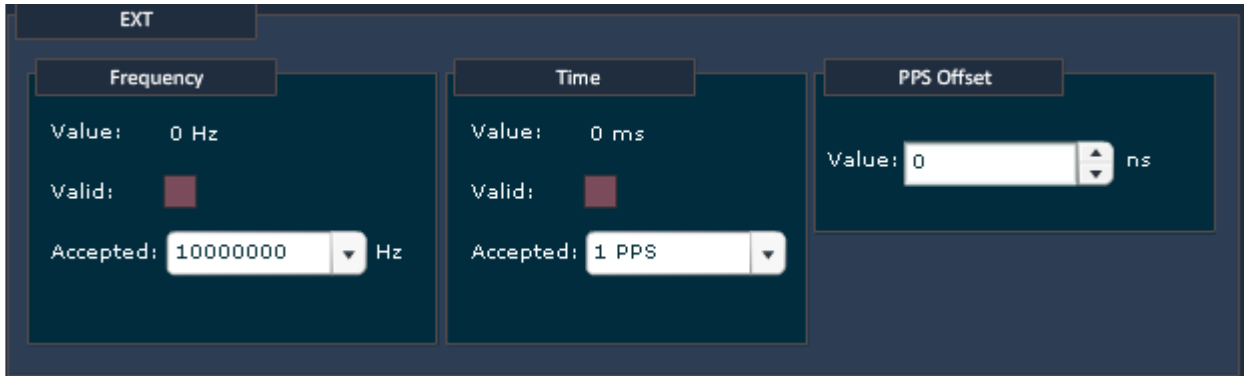
These values are displayed in the *EXT* tab of *Main Panel*.



Settings

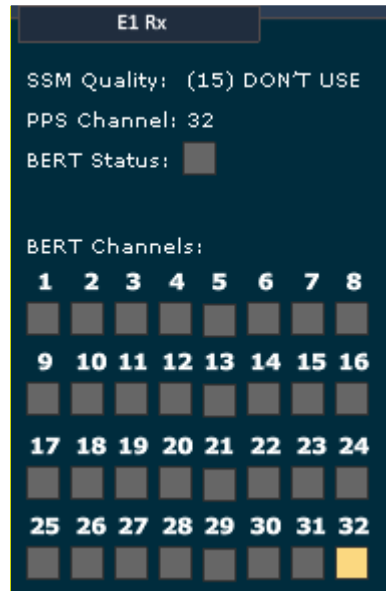
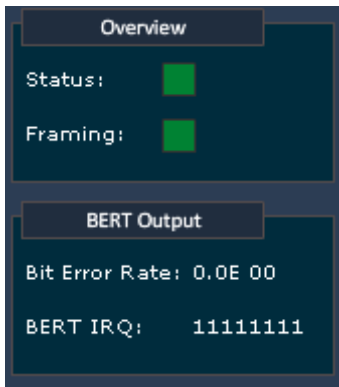
Allows to set the eligible values for the time and frequency reference between the pre-set.

These values are configurable by the *GPS / EXT / PTP Config Panel*.



E1

For informations concerning the E1 status variables, see paragraph "E1" and specifically subsections "status information" and "settings available."
 In the web interface it's possible view the values of state variables of the settings in Tab *E1* of the *Main Panel*, while is possible change the settings on the *E1 Config Panel*.



PPS Timeslot Rx: <input type="text" value="2"/> Tx: <input type="text" value="2"/>	SSM Column Rx: <input type="text" value="8"/> Tx: <input type="text" value="8"/>																																																																
Master/Slave Set type: <input type="text" value="slave"/> Set SSM QL: <input type="text" value="(00) Unknown"/>	BERT Status Rx: <input type="checkbox"/> Tx: <input type="checkbox"/>																																																																
Rx BERT Channels <table border="1"> <tr><td>1</td><td>2</td><td>3</td><td>4</td><td>5</td><td>6</td><td>7</td><td>8</td></tr> <tr><td>9</td><td>10</td><td>11</td><td>12</td><td>13</td><td>14</td><td>15</td><td>16</td></tr> <tr><td>17</td><td>18</td><td>19</td><td>20</td><td>21</td><td>22</td><td>23</td><td>24</td></tr> <tr><td>25</td><td>26</td><td>27</td><td>28</td><td>29</td><td>30</td><td>31</td><td>32</td></tr> </table>	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24	25	26	27	28	29	30	31	32	Tx BERT Channels <table border="1"> <tr><td>1</td><td>2</td><td>3</td><td>4</td><td>5</td><td>6</td><td>7</td><td>8</td></tr> <tr><td>9</td><td>10</td><td>11</td><td>12</td><td>13</td><td>14</td><td>15</td><td>16</td></tr> <tr><td>17</td><td>18</td><td>19</td><td>20</td><td>21</td><td>22</td><td>23</td><td>24</td></tr> <tr><td>25</td><td>26</td><td>27</td><td>28</td><td>29</td><td>30</td><td>31</td><td>32</td></tr> </table>	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24	25	26	27	28	29	30	31	32
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9	10	11	12	13	14	15	16																																																										
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17	18	19	20	21	22	23	24																																																										
25	26	27	28	29	30	31	32																																																										
PPS Offset Value: <input type="text" value="0"/> ns	PPS Insertion Value: <input type="text" value="1"/>																																																																

PTP

The PTP settings are split across two panels. The in-depth configuration is carried on in the Advanced panel, whilst the basic settings can be directly changed from the *Sources Panel*.

PTP

Enable: Type:
 Unicast: Profile:
 Multicast:

IP Dest 1:
 IP Dest 2:

Enable

Allows to switch on or off the PTP.

Type

Allows to choose to configure the device as a Grandmaster or a Slave.

Profile

Allows to choose to choose between some predefined profiles for common configurations.

Multicast/Unicast

Allow to choose the type of communication mechanism.

IP Dest

Allows to define a series of additional unicast addresses.

Advanced

Allows to configure a set of advanced settings.

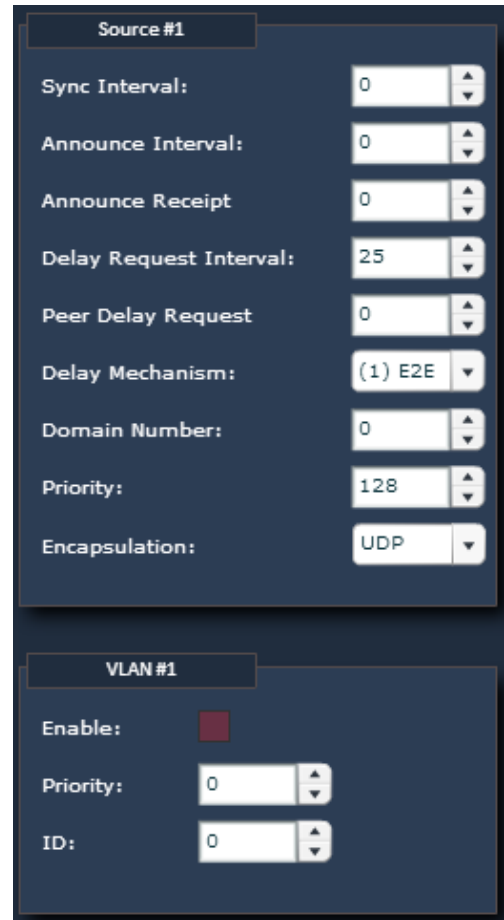
Intervals

The various interval values are expressed in power of 2, so 0 corresponds to 1 second, 1 to 2 seconds and -1 to 0.5 seconds.

VLAN

Allow to enable or disable the 802.1Q protocol.

Follows a comparative table of the various profiles. In order to customize some specific values a CUSTOM profile must be chosen.



	DEFAULT	TELECOM	POWER
Sync	1/s	32/s	1/s
Announce	2s	8/s	1/s
Announce timeout	12s	0.25s	6s
Delay Request	8s	32/s	-
Peer Delay Request	-	-	1/s
Delay Mechanism	E2E	E2E	P2P
Domain Number	0	4	0
Encapsulation	UDP	UDP	Layer2
Routing	MULTICAST	UNICAST	MULTICAST

IRIG-B

The only two settings related to the IRIG-B block are the input selector (IRIG-B Mux) and the Timezone.

NTP

Mute

Do not reply to any NTP request before synchronization is completed and time reference is valid. If the time reference is invalid the *clock unsynchronized* is risen, but some clients may not check the flag and blindly trust the time value. This setting is for additional safety.

Hardware

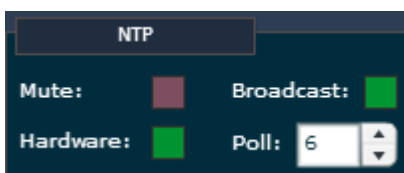
Enable NTP hardware timestamping support for improved performance (disables PTP)

Broadcast

Periodically send broadcast NTP server packets (without authentication)

Poll

Specify the interval between broadcast packets



Event Log

On the WEB is available the apparatus log from *Event log* section.
 50 entries are presented.
 It is possible to delete the logs and save them in *csv*. format.

ID	Date	Time	Code	Description
1	09/12/09	10:41:59	003	PPS Al. 1
2	09/12/09	10:41:59	003	PPS Al. 2
3	09/12/09	10:41:59	003	PPS Al. 3
4	09/12/09	10:41:59	003	PPS Al. 4
5	09/12/09	10:41:59	003	PPS Al. 5
6	09/12/09	10:41:59	003	PPS Al. 6
7	09/12/09	10:50:51	011	PPS Syncr
8				
9				
10				
11				
12				
13				
14				
15				
16				
17				
18				
19				

Load data...
Save to CSV
Clear data

Events related to the board

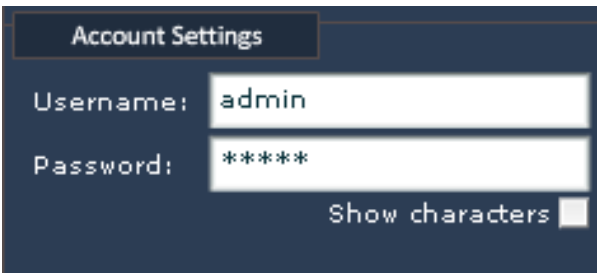
- Event Code 001 Power ON → Apparatus on
- Event Code 002 Switch → Switching on GPS / EXT / E1 source
- Event Code 003 PPS alarm → Alarm on PPS (1÷4)
- Event Code 004 Clock alarm → Alarm on 10 MHz (1÷4) signal
- Event Code 005 GPS Serial → Detection or loss of connectivity of the GPS radio
- Event Code 006 Supply → Insertion or removal of a power supply (L, R)
- Event Code 007 Switch Alarm → More than 3 exchanges in less than 5 minutes
- Event Code 008 GPS PPS → Status change of PPS from satellite
- Event Code 009 GPS Antenna → GPS antenna connection or disconnection
- Event Code 010 Bad Vtune → Vtune incorrect value
- Event Code 011 PPS Syncr → Synchronization completed
- Event Code 012 E1 Signal → Change in the status of the presence of the E1 signal
- Event Code 013 E1 Frame → Change in the status of the presence of the E1 framing
- Event Code 014 E1 PPS → Change in the status of the presence of the E1 PPS
- Event Code 015 EXT Freq → Change in the status of the presence of the EXT frequency
- Event Code 016 EXT Time → Change in the status of the presence of the EXT time
- Event Code 018 PTP PPS → Change in the status of the PPS rebuilt by PTP
- Event Code 019 IRIG-B → Change in the status of the presence of the IRIG-B signal

SNMP Trap Management

For each event related to the board, is generated a trap in parallel parallel to the machine set under TrapDest. The trap number reflects the event number and the contents of the SNMP variable associated contains the details (for example, the channel referred to the event).

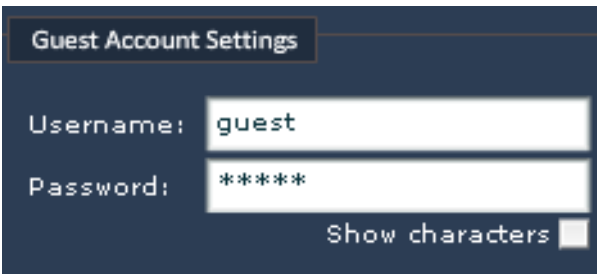
User Account

The main user who has access to the apparatus is the administrator. He is able to change its credentials under *Account Settings*.



It's possible set a user account that is able to use the apparatus remotely in read-only mode, without the possibility of changing its configuration.

The username and password for this *guest* account can be set by the administrator under *Guest Account Settings*.



The default credentials are:

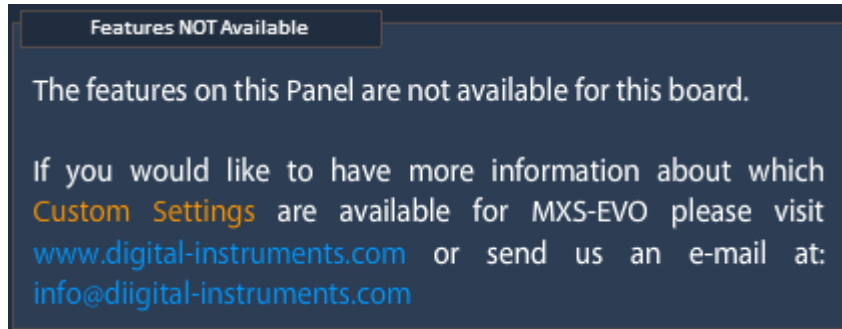
admin	→	admin / admin
guest	→	guest / guest

About SNMP:

Read community string	→	public
Write community string	→	public

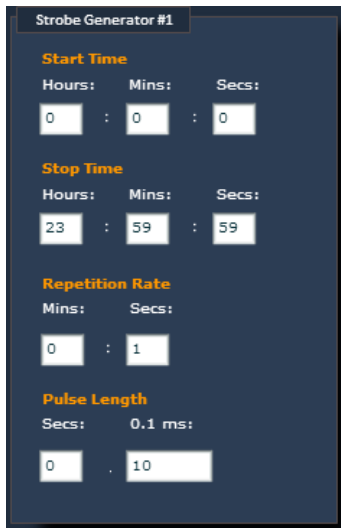
Custom Settings

The device permits to have some ad-hoc customizations through the unlock with particular activation codes.



Pulse Generation

The device is able to generate a programmable pulse in place of the IRIG-B DCLS signal (on the BNC connector) or the PPS signal.



The following parameters can be set:

- <Start Time> HH:MM:SS
- <Stop Time> HH:MM:SS
- <Repetition Rate> MM:SS
- <Pulse Length> SS.ssss

The system generates a sequence of pulses of <Pulse Length> length and repeating every <Repetition Rate> starting at <Start Time> and stopping at <Stop Time>.

Please note that the <Start Time> is always synchronous to the internal PPS (eventually disciplined via an external source).

Clock Generation

The device is able to generate two distinct programmable square wave clocks by dividing two different sources with integer dividers:

- 10 MHz
- 16.384 MHz

Please note that the rising edge of the resulting clock is synchronous to the internal PPS, if the frequency is integer.



First Run

First Installation

1. Connect at least one of the possible sources (GPS, EXT, E1, PTP, IRIG-B) in the following way:
 - GPS: connect the GPS antenna cable to the proper GPS ANTENNA socket on the rear.
 - EXT: connect a frequency or time reference on the proper connector on the rear.
 - E1: connect an E1 connector on the proper input socket on the back.
 - PTP: connect an ethernet cable to the ethernet port on the back (network should be IEEE 1588 compliant for best performance)
 - IRIG-B: connect a coax or optical connector on the proper sockets on the back (and select the proper input in the IRIG-B Mux selection)
2. Connect the MXS-EVO to the power grid.

After a few seconds the LCD display should light up (without an ethernet cable it would take a little more) and the leds under the keyboard should start blinking.

Checkup

When booted the device starts forcing the following configuration:

- Remote mode selected

Follows this simple procedure to verify the correct behaviour of the apparatus:

- Connected sources are being correctly recognized
 - Navigate to *GPS* → *Status* and check that the GPS radio is being recognized
Go to *GPS* → *Show Global Info* and check the status of the *Antenna* entry
 - Navigate to *EXT* → *Frequency Ref.* and check that the frequency source is valid. Eventually modify the accepted frequency under *EXT* → *Settings*
 - Navigate to *EXT* → *Time Ref.* and check that the time source is valid.
 - Navigate to *E1* → *Status* and check that the E1 signal and E1 framing are both valid.
 - If the PTP protocol is needed check if it is enabled under *PTP* → *Enabled*
 - Check the status of the PTP signal by navigating to *PTP* → *Status* and verifying that *SLAVE* is reported
 - Check the status of the IRIG-B signal by navigating to *IRIG-B* → *Status* and verifying that the signal is present and the date is valid
- It is possible to immediately check the status of the various sources by looking at the leds on the front panel.

Local/remote mode

The device can be used in two different modes:

1. *Local*
It is possible to change the device settings only from the front panel
Info are visible in read-only mode from WEB, SNMP or via TLS
2. *Remote*
Info are visible in read-only mode from the front panel
It is possible to change device settings from WEB, SNMP or TLC

To change mode operate the *Mode Menu* → *Local/Remote* setting from the front panel.

Network configuration

To configure the network is possible to operate via the front panel under the *Network* menu. A reboot is required for the changes to take effect.

After having got a valid IP address it is possible to connect with the device via WEB by using a common browser at the address `http://<board_ip>`

The default credentials are:

administrator (read and write) → **admin / admin**
guest (read only) → **guest / guest**

From here, it's possible to check:

- Presence of the GPS antenna
In the *GPS* tab of the *Main Panel* the *Antenna* led should be green and, after a few minutes from the boot, the *PPS Status* led should become green, too.
- Presence of the Ext. Frequency signal
In the *Ext* tab of the *Main Panel* the *Valid* led of the *Frequency* box should be green. If not do eventually modify the expected frequency in the *GPS/EXT Config Panel*.
- Presence of the Ext. Timing signal
In the *Ext* tab of the *Main Panel* the *Valid* led of the *Time* box should be green.
- Presence of the E1 signal
In the *E1* tab of the *Main Panel* the *Signal* and *Framing* leds should be green.
- Presence of the PTP signal
In the *PTP* tab of the *Main Panel* the *Enabled* led should be green and *Status* should display *Slave*.
- Presence of the IRIG-B signal
In the *IRIG-B* tab of the *Main Panel* the *Present* led should be green and *Date* should display a valid date.

Automatic switchover

In order to enable the automatic switchover is better to first check a few settings:

- **Switchover policies**
It is possible to set different policies for the switch.
These policies can be set from the front panel (*Board Settings* → *Policy*), from SNMP (*policy*) or from WEB in the *Board Configuration* page.
- **Switchover treshold**
It is possible to set a treshold to wait before switching to another source.
These policies can be set from the front panel (*Board Settings* → *Switchover*), from SNMP (*switchover*) or from WEB in the *Board Configuration* page.
- **Disciplining mode**
It is possible to specify if the disciplining from the external frequency or from E1 has to be done in frequency or phase.
- **Automatic switchover**
To finally enable the automatic switchover is possible to operate from the front panel (*Board Settings* → *Manual/Auto*), from SNMP (*switchMode*) or from WEB in the *Board Configuratio* page.

Appendix A: Quality Factor

General Review

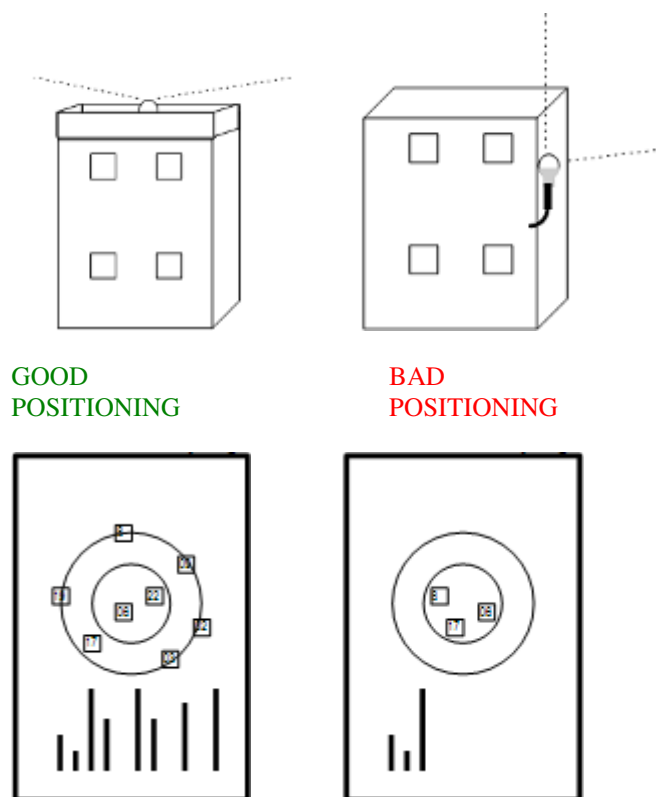
This appendix is intended to illustrate the meaning and motivation of the introduction of the Quality Factor within the Digital Instruments equipments.

Although the installation of a GPS device is relatively easy, it can hide certain issues that in some cases it can affect the proper functioning.

It is therefore expected to monitoring certain operating parameters so as to make immediate validation of a Circuit or finding the source of any problems.

GPS antenna positioning

GPS antenna should be positioned on a tower or on a roof with a good view of the GPS satellite constellation.



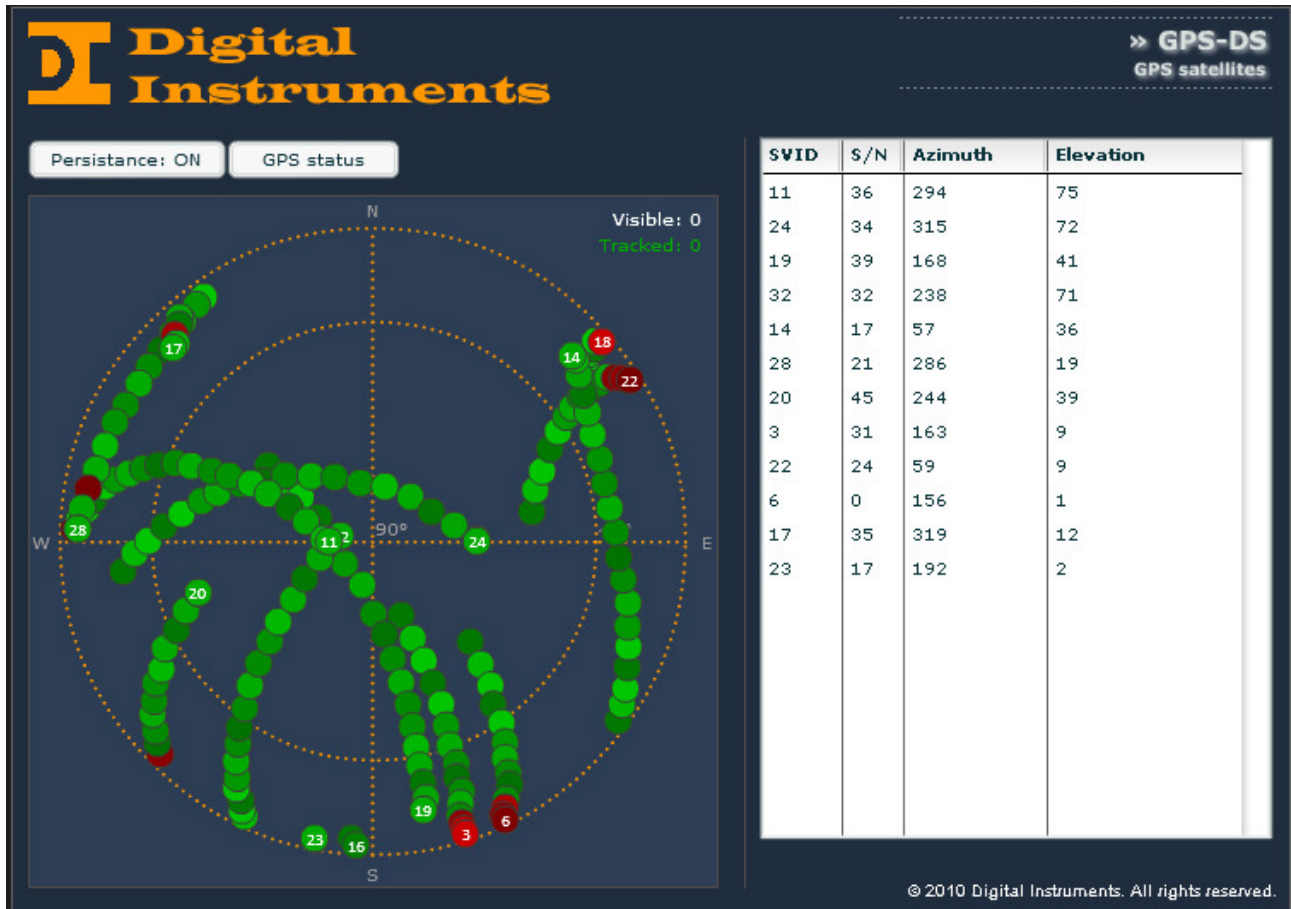
If not, the algorithm of regulation may not behave optimally and *short term stability* of the PPS and 10 MHz references it could be invalidated.

It's possible to evaluate the goodness of the positioning of the antenna in some ways:

1. checking the **power of received signal** from each satellite from the *Polar Plot*
2. checking and verifying that the **Quality Factor** is acceptable (typically > 25)
3. checking that the PPS generated by the radio (**PPS Status**) is valid (green LED)

Se così non fosse l'algoritmo di disciplinamento potrebbe non comportarsi in maniera ottimale e la *short term stability* dei riferimenti PPS e 10 MHz ne potrebbe venire inficiata.

It's possible get an idea of potential obstacles that limit the visibility of the GPS constellation to the radio observing the polar graph of satellites after a few hours of persistence.



Quality Factor

Quality Factor is the operating parameter that indicates the quality of the GPS signal received by the antenna. It is considered an acceptable value if > 25. If the Q.F. is lower, it is possible that there are problems with the GPS signal reception and this involves a greater number of holdover and therefore a less precise synchronization.

The value of the Quality Factor is shown in *GPS* tab of *Main Panel* Page.

PPS Status: ■
 PPS Sync: ■
 Antenna: ■
 Position: ■
 Quality: ■ 28

Statistics

The device stores some useful statistical informations to evaluate the proper functioning over time:

- Holdover Num** shows the number of times that the GPS radio has entered into holdover mode in response to a problem (under optimal conditions should be low)
- Holdover Max** shows the duration of the longer hold-over (under optimal conditions should be low)
- Quality Min** indicates the smallest GPS antenna quality factor recorded (under optimal conditions should be high)
- PPS Dist Max** indicates the maximum distance affected by the PPS generated by the GPS radio (under optimal conditions should be low)
- Pos Alarm Num** indicates the number of times that there was a wrong geo-positioning under optimal conditions should be low)



It's a good idea to reset the stats before a capture session, because some values may be spurious in the first phase of synchronization or acquisition of satellites by the GPS radio.

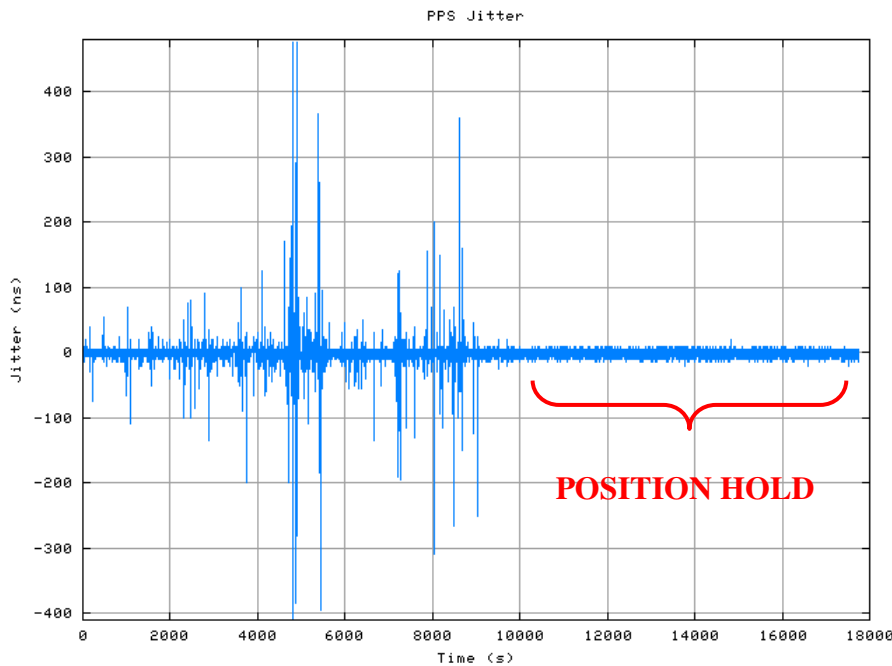
Automatic Site Survey



In certain situations it may be convenient activate the *Positioning Mode* of GPS radio in *Automatic Site Survey*. In this mode the radio privileges the accuracy of temporal information at the expense of that position (as long as the antenna is not moved), so as to preserve signal integrity PPS in limited visibility conditions or in the GPS constellation or in presence of potential sources of interference.



If there are problems or abnormalities during the first installation or after moving the unit in a distant geographic location, GPS radio can be resetted by deleting the almanac and positioning information that is saved by the appropriate entry in the GPS menu. Should be also necessary to reset the device in *Automatic Site Survey* mode, since the radio, after completing the survey - which takes about 3 hours - automatically returns to *Position Hold* mode.



Appendix B: FAQ

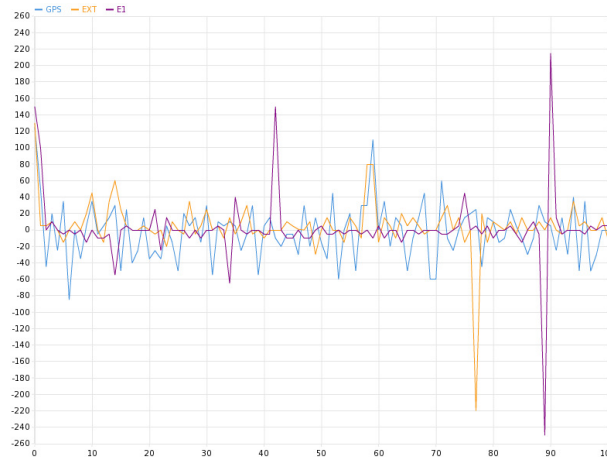
D: How is it possible to certify the various time references?

R: In order to certify a particular reference is better to have the device disciplined by GPS or from another stable source.

In this way is possible to evaluate the jitter of the reconstructed PPS in different ways:

1. by asking the device the log of the last 6 hours

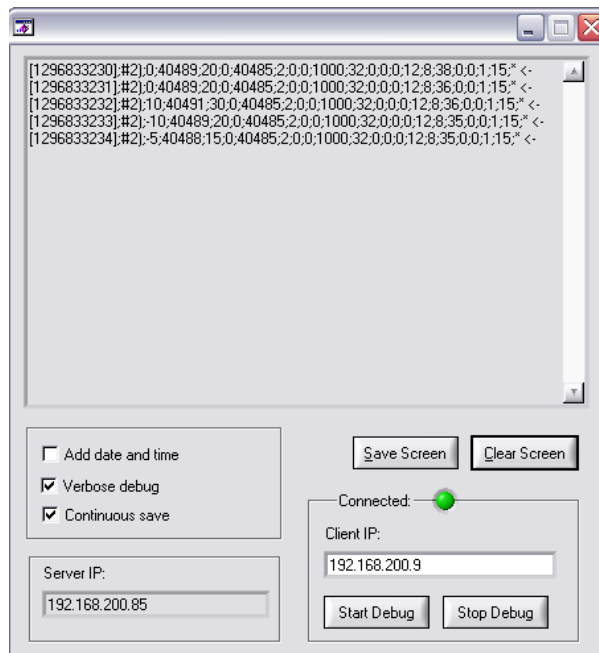
<http://x.x.x.x/cgi-bin/savestability>



2. by letting an external event logger collect the data (e.g. AON Console Manager)
3. by using a debug utility to retrieve the live values (distance, jitter, validity) and by post-processing them. <ftp://digiguest:guestd@www.digital-instruments.it/Server%20TCP%20v2.zip>

To do so is simply necessary to launch the utility and specify the correct IP address of the device. Is better to configure the utility with the following settings.

Add date and time OFF
 Verbose debug ON
 Continuous save ON



Press the *Save Screen* button and specify a file on which to save the data. The acquisition is now started and ends when the utility is closed. If the *Continuous save* field is not enabled is possible to press *Save Screen* in order to save the data currently acquired (it may slow down the PC if there is much data to save).

The resulting file is a simple csv that may be edited and viewed by a common spreadsheet program (e.g. Microsoft Excel).

Follows the complete list of all the values that are exported:

Time	number of seconds since epoch (1st January 1970)
SRC num	number of reference (1 → GPS, 2 → EXT, 3 → E1, 4 → PTP, 5 → IRIG-B)
PPS jitter (ns)	short-term stability of the source PPS
Vtune corrente	current vtune value of the OCXO
PPS distance (ns)	distance of the source PPS against the reference PPS
holdover num (s)	number of seconds from which the device is not disciplining
Vtune stabile	last stable vtune
Sync num	number of PPS resyncs
Antenna status	antenna status (0 → OK)
T-RAIM solution	PPS status (0 → OK)
T-RAIM alarm (ns)	maximum distance of the reconstructed PPS in order to be considered valid
T-RAIM error (ns)	GPS PPS accuracy
GPS error	GPS PPS error
Visible sats	number of visible satellites
Tracked sats	number of tracked satellites
Quality factor	quality factor (based on the GPS antenna, > 25 → OK)
need_pps_reset	(internal use)
need_pwm_duty_stable	(internal use)
pps_polarization	(internal use)
pwm_speed_limit	(internal use)
Sync done	* locked
Master	<- currently selected source

Is suggested to:

1. Collect the data as previously explained in .csv format (using *Continuous save* option)
2. open Excel and apply an automatic filter on the 2nd column (the one of the source number with the #)
3. initially filter based on source #1 (GPS) and verify that the 5th column (PPS distance) would contain values near 100 ns (the base unit is the ns)
4. subsequently filter based on the other sources #2 (EXT), #3 (E1), #4 (PTP) o #5 (IRIG-B) and plot the 5th column (it shows the precision of the reconstructed PPS).

D: Is it possible to reach NTP stability below 1 ms?

R: Yes. In order to achieve sub-ms precision it is necessary to enable the NTP hardware timestamping support. In this way is possible to have timestamps accurate to better than 100 ns.

Please note that the client device should be able to cope with the interleaved mode (please refer to NTP section for further details).

In Windows Vista and Seven a few additional steps may be required to improve the performance:

- Disable CPU spread spectrum capabilities in the BIOS
- Disable CPU frequency scaling capabilities
- Set the following environmental variable:

NTPD_USE_INTERP_DANGEROUS=1

If nothing works you it may also possible to try with the serial port. The device outputs a NMEA stream @ 9600 bps 8/N/1 and triggers the PPS on pin 1 (DCD)

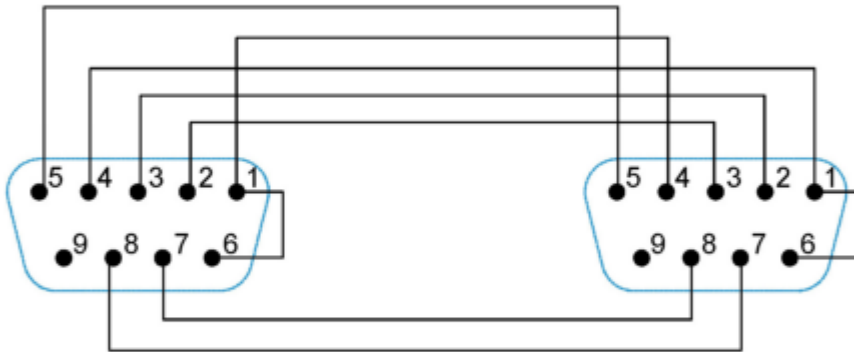
The following configuration may be used in ntpd.conf:

```
server 127.127.20.1 minpoll 4 maxpoll 4 mode 24 # NMEA @ 9600 bps, $GPZDA
fudge 127.127.20.1 time2 0.0110185 # time correction
```

A NULL modem cable should be used to connect with the device on the serial port.

The schematic is depicted here:

RS232 NULL MODEM CABLE



In particolare devono essere invertiti i fili:

2 e 3 (TX- RX)

4 e 6 (DTR - DSR)

7 e 8 (RTS - CTS)

Appendix C: Changelog

Release 1.0 (december 2011)

- First release

Release 1.1 (february 2012)

- Added support for IRIG-B

Release 1.2 (march 2012)

- Added support for Synchronous Ethernet

Release 1.3 (april 2012)

- Enhanced disciplining of the NTP server

Release 1.4 (june 2012)

- Enhanced recognition of the external frequency
- Added support for hardware upgrade

Release 1.5 (august 2012)

- NTP server even without GPS
- Auto-recognition of the IRIG-B input
- IRIG-B robustness increased

Release 1.6 (september 2012)

- SyncE management simplified

Release 1.7 (october 2012)

- Added clock generation support

Release 1.8 (october 2012)

- Added handling of the ESMC packets for the SyncE

Release 1.9 (november 2012)

- Added timing information over E1

Release 2.0 (january 2013)

- Added PTP custom parameters
- Added disciplining parameters in the PTP Announce Message
- Added support for PTPv2 unicast through signalling messages

Release 2.1 (january 2013)

- Added support for PTP over Layer 2 and VLAN (802.1Q)

Release 2.2 (january 2013)

- Software libraries updated

Release 2.3 (february 2013)

- Resync of the PPS when disciplining in frequency only when necessary

Release 2.4 (march 2013)

- Added support for NMEA GPS radio

Release 2.5 (april 2013)

- Updated GUI to fix some problems in the E1 panel

Release 2.6 (august 2013)

- Updated PTP settings

Release 2.7 (september 2013)

- Added multiple VLAN support

Release 2.8 (october 2013)

- Added support for NTP hardware timestamping

Release 2.9 (october 2013)

- Added support for PPS over serial line

Assistance

For support requests please download the form from the website:

<http://www.digital-instruments.it/ita/assistenza.php>

Compile it in its entirety by specifying as precisely as possible and giving as many details as possible about the type of fault detected.

You can then send the form to **riparazioni@digital-instruments.com**, via fax to **+39.02.66506103**, or enter it directly into the box when sending goods for repair.

You can also contact us at +39.02.66506250 Monday to Friday from 9 to 13 and from 14 to 17 (GMT+1 Time).

Technical Data

Programmable outputs

Outputs	12
Signals	PPS, IRIG-B DCLS, IRIG-B AM, E1, 2.048 MHz, 10 MHz
Output impedance	50 Ω
Output connector	BNC

Frequency Reference

Signal	10 MHz sine wave, 2.048 MHz sine wave
Spectral Purity	-70 dBc (harmonic) -75 dBc (non-harmonic)
Phase noise	-130 dBc at 1kHz
Output level	13 dBm
Output impedance	50 Ω
Output connector	BNC
Stability	1e-12 daily average (OCXO locked to GPS on SA) 1e-10 daily average (OCXO free run)

Time Reference

Signal	1 PPS, 100 μ s Duty, Rising Edge
Output level	TTL 5 Vpp, Square wave
Output impedance	50 Ω
Output connector	BNC

GPS Section

Receiver	12 Channels L1 1575.42 MHz
Tracking	Correlation on 12 satellites
PPS accuracy	< 50 ns on SA
Antenna connector	TNC
Collection time	< 4 min

External Section

Frequency Reference

Standard frequencies	1MHz, 2MHz, 2.048MHz, 5 MHz, 10 MHz
Input level	From -2 dBm to 16 dBm, sine wave

Time Reference

Standard periods	1 PPS
Input level	TTL 5 Vpp, square wave

Input impedance	50 Ω
Input connector	BNC

E1 Section

Standard signal	E1 256S multiframe (16 frame for each multi frame) CRC-4
Input/Output impedance	75 Ω
Input/Output connector	BNC

PTP Section

Protocol	IEEE 1588-2008 (PTPv2)
Role	Grandmaster clock source (GPS) or slave
Time stamping	Hardware
Precision	< 1 μ s

NTP Section

Protocol	NTP version 4
Role	Grandmaster clock source (GPS)
Stratum	1
Precision	< 10 ms with software timestamping

< 100 ns with hardware timestamping (disables PTP)

IRIG Section

Format	B
Modulation	Pulse width modulated / Amplitude modulated
Frequency	DC / 1 KHz
Information sent	TOY (BCD), Year (BCD)
Connector	BNC (electrical) or ST (optical 850 nm multimodal)

Signaling

Network connection	N° 1 Ethernet 10/100 interfaces, TCP/IP protocol
Signaling	N° 7 led on front panel
Serial Connection	RS-232 connector DB9 Male +/- 15 kV (ESD)
Remote signalling	7 Dry contact on Weidmuller connector with 3.5 mm step
Remote controllers	4 Dry contact on Weidmuller connector with 3.5 mm step

Supply

Input	N° 2 independent supply
Network	95 Vac < > 240 Vac Plug IEC320 integrated, filter EMI/RFI

Sizes

Width	1 Unit 19''
Depth	300 mm without connectors
Weight	1.5 Kg

Accessories

1 x GPS Antenna
 1 x 30 m Belden PRG 7 Cable
 2 m Cordon for network supply
 Handbook in English/Italian